

# Ampere's Law

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# Ampere's Law

$$\vec{\nabla} \times \vec{\mathbf{B}} = \mu_0 \vec{\mathbf{J}}$$

- ▶ The curl of magnetic field at a point in space is proportional to the current density at that point.
- ▶ Where current points in the direction of your right thumb, magnetic field points in the direction of your bent right fingers.
- ▶ The equation above is called the *differential form* of Ampere's law.

## Deriving the integral form of Ampere's Law

- ▶ Start with the differential form of Ampere's law.

$$\vec{\nabla} \times \vec{\mathbf{B}} = \mu_0 \vec{\mathbf{J}}$$

- ▶ Pick any oriented surface  $S$ . Do a flux integral of both sides of Ampere's law using this surface  $S$ .

$$\int_S (\vec{\nabla} \times \vec{\mathbf{B}}) \cdot d\vec{\mathbf{a}} = \mu_0 \int_S \vec{\mathbf{J}} \cdot d\vec{\mathbf{a}}$$

- ▶ Use Stokes' theorem to rewrite the left side. Realize that the integral on the right side is the current flowing through the surface.

$$\int_{\partial S} \vec{\mathbf{B}} \cdot d\vec{\ell} = \mu_0 I_{\text{enc}}$$

- ▶ The term on the left is the magnetic circulation around the boundary of  $S$ .

## Integral form of Ampere's Law

$$\int_C \vec{\mathbf{B}} \cdot d\vec{\ell} = \mu_0 I_{\text{enc}}$$

- ▶  $C$  is any closed curve or loop.
- ▶  $I_{\text{enc}}$  is the current flowing through  $C$ .
- ▶ The magnetic circulation around a closed loop  $C$  is proportional to the current enclosed by the loop.
- ▶ Ampere's law is not a recipe for finding anything.
- ▶ It is a claim that magnetic field and current are related.
- ▶ Current gives rise to magnetic field.
- ▶ If a current distribution has high symmetry, we can use the integral form of Ampere's law to find the magnetic field produced by the current distribution.

## Using Ampere's law to find the magnetic field when the current distribution has cylindrical symmetry

- ▶ Any rotation about the symmetry axis leaves the current distribution unchanged, and hence must leave the magnetic field unchanged.
- ▶ Any translation parallel to the symmetry axis leaves the current distribution unchanged, and hence must leave the magnetic field unchanged.
- ▶ Cylindrical symmetry has two cases, one for current distributions that are like a long straight wire, and one for distributions that are like a solenoid.

# Cylindrical Symmetry Case 1

- ▶  $\vec{\mathbf{J}}$  depends only on  $s$ , not on  $\phi$  or  $z$ , and  $\vec{\mathbf{J}}$  points in the  $\hat{\mathbf{z}}$  direction.

$$\vec{\mathbf{J}} = J(s)\hat{\mathbf{z}}$$

- ▶ The magnetic field must point in the  $\hat{\phi}$  direction:  $\vec{\mathbf{B}} = B(s)\hat{\phi}$ .
- ▶ The azimuthal component  $B(s)$  of the magnetic field can depend only on  $s$ , not on  $\phi$  or  $z$ .
- ▶ Choose a circle of radius  $s$  as your Amperian loop  $C$ . Notice that

$$\int_C \vec{\mathbf{B}} \cdot d\vec{\ell} = B(s)2\pi s.$$

## Cylindrical Symmetry Case 2

- ▶  $\vec{\mathbf{J}}$  points in the  $\hat{\phi}$  direction; the magnitude of  $\vec{\mathbf{J}}$  depends only on  $s$ , not on  $\phi$  or  $z$ .

$$\vec{\mathbf{J}} = J(s)\hat{\phi}$$

- ▶ The magnetic field must point in the  $\hat{z}$  direction:  $\vec{\mathbf{B}} = B(s)\hat{z}$ .
- ▶ The  $\hat{z}$  component  $B(s)$  of the magnetic field can depend only on  $s$ , not on  $\phi$  or  $z$ .
- ▶ Choose a rectangle as your Amperian loop  $C$ . The sides parallel to the  $\hat{z}$  direction have length  $L$ . The sides parallel to the  $\hat{s}$  direction extend from  $s_1$  to  $s_2$ . Notice that

$$\int_C \vec{\mathbf{B}} \cdot d\vec{\ell} = B(s_2)L - B(s_1)L.$$

## Using Ampere's law to find the magnetic field when the current distribution has planar symmetry

- ▶ With planar symmetry,  $\vec{\mathbf{J}}$  points in the  $\hat{\mathbf{x}}$  direction; the magnitude of  $\vec{\mathbf{J}}$  depends only on  $z$ , not on  $x$  or  $y$ .

$$\vec{\mathbf{J}} = J(z)\hat{\mathbf{x}}$$

- ▶ Any translation in the  $xy$  plane leaves the current distribution unchanged, and hence must leave the magnetic field unchanged.
- ▶ The magnetic field must point in the  $\hat{\mathbf{y}}$  direction:  $\vec{\mathbf{B}} = B(z)\hat{\mathbf{y}}$ .
- ▶ The  $\hat{\mathbf{y}}$  component  $B(z)$  of the magnetic field can depend only on  $z$ , not on  $x$  or  $y$ .
- ▶ Choose a rectangle as your Amperian loop  $C$ . The sides parallel to the  $\hat{\mathbf{y}}$  direction have length  $L$ . The sides parallel to the  $\hat{\mathbf{z}}$  direction extend from  $z_1$  to  $z_2$ . Notice that

$$\int_C \vec{\mathbf{B}} \cdot d\vec{\ell} = B(z_1)L - B(z_2)L.$$